ROBOT JOINT SERVO DRIVE

WEC-D048/05-FS002D-EC (Diameter: Outer 70mm, Inner 15mm)

Ratings	05
Motor Output Continuous Output Current Arms	5
Motor Output Peak Output Current Arms	10

	Basic Specifications Descriptions			
Feature		Specification		
Motors	DC/BLDC/PMSM/VCM	Rotary servo motors, Linear servo motors		
Current (Torque) Control	Control Periodic	20KHz		
	Control Loop	PI + Feed-forward		
Velocity & Position Control	Control Periodic	2KHz		
	Control Loop	Cascade P/PI + Feed-forward		
	Filters	First order low pass filter, Four notch filters, First order adaptive windowing filters,		
Reference Command	Current / Velocity / Position	CANopen + EtherCAT(CoE)		
Auto Tuning	Method	Automatic self-configuration and optimization of motor phasing, wires, current loop, velocity control loop.		
Brake	Method	Control stops : Several Dynamic brake and Active disable options		
GUI	User Interface	WELSS(WelconServoStudio), Setting, Drive, Motor, Feedback, I/O, Motion,		
Protective Functions	Under- and over-voltage, Over-current, Over-load(with I ² T), Drive over-temperature, Feedback sensor signal lost			
Compliance Standard	CE, KC	CE, KC		
Environment	Ambient temperature : Operatio	• Ambient temperature : Operation 0-45 °C, Storage 0-70 °C • Humidity : 10-90% • Vibration : 1.0g		

Communication			
Feature	Specification Specification		
CAN	CANopen – CiA 301 application layer and CiA 402 device profile for drives and motion control Baud rate 0.125M 1M bit/s		
EtherCAT CiA 301 application layer and CiA 402 device profile for drives and motion control Communication cycle time: up to 500 μs(CSV, CSP mode), up to 250us(CST mode)			

I/0*			
Feature	Specification		
Analog Input	Quantity	1	
	Voltage Range	Analog ±10 VDC differential	
	Input Resolution	12bit	

Motor Feedback*			
Feature	Specification		
General	Supply Voltage	5VDC	
Incremental Encoder	Signal	A-quad-B with or without index, shared digital hall sensor, RS422, Differential	
	A-quad-B Max Input Frequency	10MHz (before quadrature)	
Digital Hall Sensor	Signal	Differential-ended	
	Туре	Separated and shared hall sensor	
Serial Encoder	Туре	SSI, Biss C	
	Bite rate	0.5Mbps, 1Mbps, 2Mbps, 2.5Mbps, 5Mbps	



